Hanchen Xiong

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	University of Innsbruck	\boxtimes : hanchenx@gmail.com	
	Innsbruck, A-6020, Austria	: iis.uibk.ac.at/public/xiong	g
Research Interests	Machine learning, Bayesian statistics, Computer Vision, Computational Neuroscience, Robotics Probabilistic graphical models, structured output learning, mulit-label prediction, Bayesian learn- ing, kernel machines, advanced Markov chain Monte Carlo methods, neural networks, approximate inference, visual understanding, sensori-motor learning, robotic cognition learning.		
Education	University of Innsbruck, Innsbruck, Austria		
	Ph.D. Candidate, Computer Science		09, 2011-(expected) 04 2015
	 Dissertation: Optimization, Inference and Learning on Structure Domains: Theories and Some Applications in Visual Perception Supervisor: Pro. Dr. Justus Piater, Dr. Sandor Szedmak 		
	University College London, London, UK		
	M.Sc., Machine Learning		09, 2009-10, 2010
	 Thesis: Investigate the Use of Random Finite Sets to Track Quantum Dots (Distinction) Supervisor: Dr. Simon Julier 		
	Huaqiao University, Quanzhou, China		
	B.Eng., Computer Science and	Technology	09, 2005-07, 2009
Employment Experience	University of Innsbruck, Innsbruck, Austria		
	Researcher		04, 2011 - present
	Kuang-chi Institute of Advanced Technology, Shengzhen, China		
	Machine Learning Engineer		10, 2010 - 01, 2011
Projects	EU FP7 (European Union Seventh Framework Program) project "Xperience", grant agreement Nr. 270273.		
Publication List	Hanchen Xiong, Sandor Szedmak, Justus Piater. Implicit Learning of Simpler Output Kernels for Multi-Lable Prediction, NIPS workshop on Representation and Learning Methods for Complex Outputs (NIPS-RLCO2014).		
	Hanchen Xiong, Sandor Szedmak, Justus Piater. Towards Maximum Likelihood: Learning Undi- rected Graphical Models using Persistent Sequential Monte Carlo, The 6th Asian Conference on Machine Learning (ACML2014), Best Paper Award. Recommended to Machine Learning journal with longer version.		
	Hanchen Xiong, Sandor Szedmak, Justus Piater. Scalable, Accurate Image Annotation with Joint SVMs and Output Kernels, Accepted (As one of selected papers from ESANN 2014 for Neurocomputing).		

Hanchen Xiong, Sandor Szedmak, Antonio Rodríguez Sánchez, Justus Piater. Towards Sparsity and Selectivity: Bayesian Learning of Restricted Boltzmann Machine for Early Visual Features, In Proceedings of the 24th International Conference on Artificial Neural Networks (ICANN14), 2013, Springer.

Hanchen Xiong, Sandor Szedmak, Justus Piater. Joint SVM for Accurate and Fast Image Tagging, In Proceedings of the 22nd European Symposium on Artificial Neural Network (ESANN14).

Hanchen Xiong, Sandor Szedmak, Justus Piater. Comparing Binary Hamiltonian Monte Carlo and Gibbs Sampling for Training Discrete MRFs with Stochastic Approximation, International Conference on Artificial Intelligence and Statistics (AISTATS14).

Wörgötter Florentin, Geib Chris, Tamosiunaite Minija, Aksoy Eren Erdal, Piater Justus, Xiong Hanchen, Ude Ales, Nemec Bojan, Kraft Dirk, Krüger Norbert, Wächter Mirko, and Asfour Tamim. Structural bootstrapping - a novel concept for the fast acquisition of action-knowledge. IEEE Transactions on Autonomous Mental Development (Submitted)

Hanchen Xiong, Sandor Szedmak, Justus Piater. 3D Object Class Geometry Modeling with Spatial Latent Dirichlet Markov Random Fields, In Proceedings of the 35th German Conference on Pattern Recognition (GCPR13), pp 51-60, 2013, Springer.

Hanchen Xiong, Sandor Szedmak, Justus Piater *Homogeneity Analysis for Object-Action Relations Reasoning in Kitchen Scenarios*, In Proceedings of 2nd Workshop on Machine Learning for Intelligent Systems (MLIS13), pp 37-44, 2013, ACM.

Hanchen Xiong, Sandor Szedmak, Justus Piater A Study of Point Cloud Registration with Probability Product Kernel Functions, In Proceedings of 2013 International Conference on 3D Vision (3DV13), pp 207-214, 2013, IEEE.

Hanchen Xiong, Sandor Szedmak, Justus Piater *Efficient, General Point Cloud Registration With Kernel Feature Maps*, In Proceedings of 10th International Conference on Computer and Robot Vision (CRV13), pp 83-90, 2013, IEEE.

Qing Lei Hanchen Xiong A New Binary-tree-based Algorithm for XML Data Model Extraction Computer Engineering and Design, Issue 13, pp 3205-3208, 2009.

INVITED TALKS Homogeneity Analysis for Object-Action Relations, Malloca, Spain Xperience Summer School

04, October, 2013

Point Cloud Registration With Kernel Feature Maps, TU Berlin, Germany DGR-Tage 2012

29,July,2012

PROFESSIONAL Program Committee

SERVICES

• 37th Annual Workshop of Austiran Association for Pattern Recognition

Reviewing

- (Journal) Frontiers in Computational Neuroscience
- IEEE Transaction on Image Processing
- IEEE Transactions on Autonomous Mental Development
- 2015 IEEE International Conference on Robotics and Automation (ICRA 2015)
- 2014 IEEE/RSJ International Conference on Robots and Systems (IROS 2014)
- 2014 IEEE International Conference on Robotics and Automation (ICRA 2014)

Skills Programming • C++, Matlab: good command • Python, Java, R: less often used Libraries and Tools OpenCV, PCL, LaTex **Operation Systems** Unix/Linux, Windows Languages • English: fluent • Mandarin: mother tone • German: beginner HONORS AND Best Paper Award, 6th Asian Conference on Machine Learning, 2014 AWARDS 2nd Provincial Prize, Programming Contest of Pan-Pearl River Delta, China, 2009 1st Provincial Prize, China Undergraduate Mathematical Contest in Modeling, 2009 2nd Provincial Prize, China Undergraduate Mathematical Contest in Modeling, 2008 Outstanding Thesis Award, Huaqiao University, China, 2009 Outstanding Graduate Award, Huaqiao University, China, 2008

• 2014 IEEE International Conference on Robotics and Automation (ICRA 2013)

End of CV. Updated on 10,02,2015