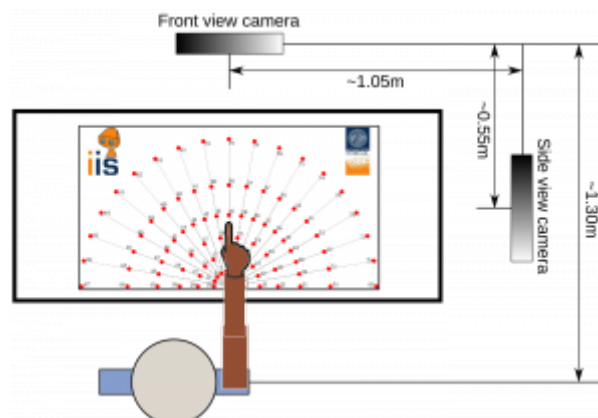


## Innsbruck Multi-View Hand Gesture (IMHG) Dataset

Hand gestures constitute a natural forms of communication in human-robot interaction scenarios. They can be used to delegate tasks from a human to a robot. To facilitate human-like interaction with robots, a major requirement for advancing in this direction is the availability of a hand gesture dataset for judging the performance of the algorithms.

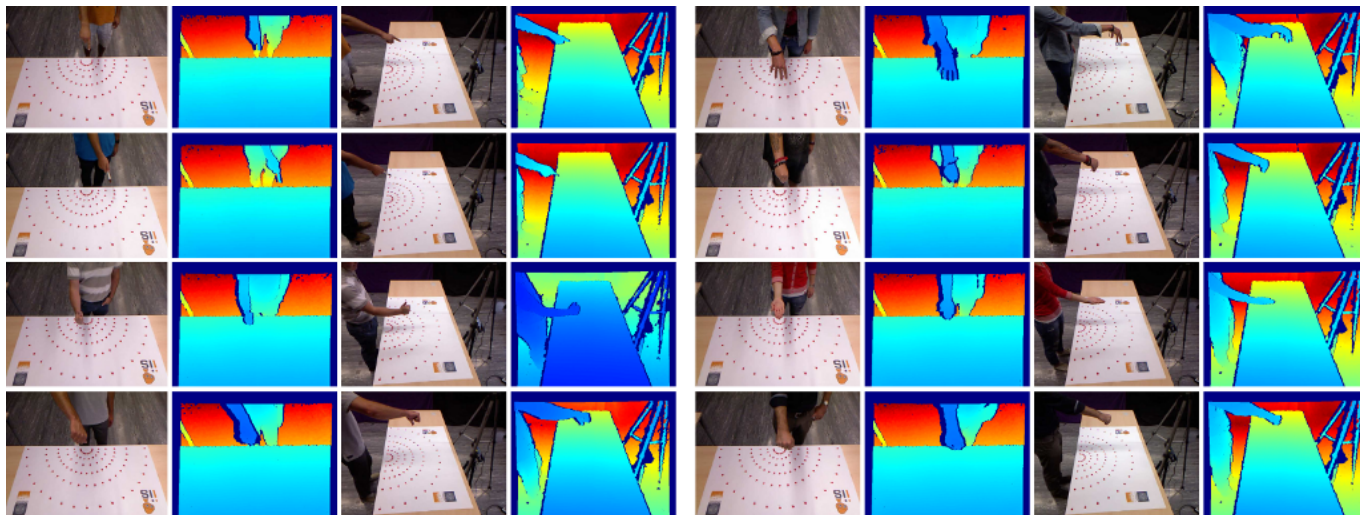
### Dataset Features

- 22 participants performed 8 hand gestures in the context of human-robot interaction scenarios taking place at close proximity.
- 8 hand gestures categorized as:
  1. 2 types of deictic gestures with the ground truth location of the target pointed at,
  2. 2 symbolic gestures,
  3. 2 manipulative gestures,
  4. 2 interactional gestures.
- A corpus of 836 test scenarios (704 reference gestures with ground truth, and 132 other gestures).
- Hand gestures recorded from two views (frontal and lateral) using an RGB-D Kinect sensor.
- The data acquisition setup can be easily recreated using a polar coordinate pattern as shown in the figure below to add new hand gestures in the future.



- Soon to be released publicly.
- Currently available for [Download](#) (~888MB) with authentication.

### Sample Scenarios



Gestures recorded from frontal and side view. *T-B*: Finger pointing, Tool pointing, Thumb up (approve), Thumb down (disapprove), Grasp open, Grasp close, Receive, Fist (stop).

## Reference

Dadhichi Shukla, Ozgur Erkent, Justus Piater, The IMHG dataset: A Multi-View Hand Gesture RGB-D Dataset for Human-Robot Interaction. Towards Standardized Experiments in Human Robot Interactions, 2015 (Workshop at IROS). Extended Abstract.[PDF](#).

## BibTex

```
@InProceedings{Shukla-2015-StandardHRI,
  title = {{The IMHG dataset: A Multi-View Hand Gesture RGB-D Dataset for Human-Robot Interaction}},
  author = {Shukla, Dadhichi and Erkent, Ozgur and Piater, Justus},
  booktitle = {{Towards Standardized Experiments in Human Robot Interactions}},
  year = 2015,
  month = 10,
  note = {Workshop at IROS},
  url = {https://iis.uibk.ac.at/public/papers/Shukla-2015-StandardHRI.pdf}
}
```

## Acknowledgement

This research has received funding from the European Community's Seventh Framework Programme FP7/2007-2013 (Specific Programme Cooperation, Theme 3, Information and Communication Technologies) under grant agreement no. 610878, [3rd HAND](#).

## Contact

[dadhichi\[dot\]shukla\[at\]uibk\[dot\]ac\[dot\]at](mailto:dadhichi@shukla@uibk.ac.at)

From:

<https://iis.uibk.ac.at/> - IIS

Permanent link:

<https://iis.uibk.ac.at/datasets/imhg?rev=1456235678>

Last update: **2018/09/03 14:57**

