2025/12/09 10:44 1/2 GMAR Robotics School 2021

# **GMAR Robotics School 2021**

Draft; do not publish

# **Organization**

Date: tentatively 2021-08-23 - 2021-08-27 (Monday-Friday)

• Location: Villa Blanka; Innsbruck

• Topic: Mobile Manipulation

#### Audience:

- advanced Master and young doctoral students in subject areas related to robotics (engineering, computer science, etc.)
- 15-25? participants, depending on the location
- prerequisite: familiarity with ROS, to be specified; recommend tutorials

## Concept:

- hands-on, making things work on real robots
- technical lectures concentrated near the beginning of the week
- hacking starting day one, growing in importance as the course advances
- hacking in small teams dedicated to specific functionalities
- some application talks towards the end, not relevant to the hacking

### Implementation Goal:

- SLAM, autonomous navigation
- vision-based grasping of (known and/or unknown?) objects from known locations
- placing objects in designated locations
- execution of high-level plans involving the above capabilities

### Robots:

- 1 mobile base + arm platform for each group of 3-4 students
- or, 1 UIBK mobile manipulator (homebrew base with DOBOT M1? Franka Emika Panda)
- or, TUW Honda mobile manipulator

# **Schedule**

Each session lasts 90 minutes; blank = hacking.

Sessions	Monday	Tuesday	Wednesday	Thursday	Friday
Morning I	Mechatronics of mobile manipulators (Johannes Gerstmayr or Colleague*)	Robot Vision (Markus Vincze or Colleague *)	Visual Servoing (Antonio Paolillo)	Industry event + Robotics talks event in <b>Alpbach</b> . Departure at 8.30am, return 15.30pm	Task Planning (Gerald Steinbauer)
Morning II	Kinematics (Andreas Müller*)	Picking and Placing (Justus Piater*) - Needed?	Hacking: Visual Servoing for Pick and Place		Hacking: <b>Team competition?</b>
Afternoon I	Dynamics, Control (Wolfgang Werth*)	Human-Robot Interaction and Safety Aspects (Mathias Brandstötter*)	ROS Navigation Stack (Matteo Saveriano)		
Afternoon II	Hacking: Set-up the robots	Hacking: Path/Motion Planning in ROS	Hacking: Navigation in ROS		
Dinner	on site	on site	on site	in town	-

<sup>\*</sup> confirmed

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