GMAR Robotics School 2021

Draft; do not publish

Organization

- Date: tentatively 2021-08-23 2021-08-27 (Monday-Friday)
- Location: Villa Blanka; Innsbruck
- Topic: Mobile Manipulation

Audience:

- advanced Master and young doctoral students in subject areas related to robotics (engineering, computer science, etc.)
- 15-25? participants, depending on the location
- prerequisite: familiarity with ROS, to be specified; recommend tutorials

Concept:

- hands-on, making things work on real robots
- technical lectures concentrated near the beginning of the week
- hacking starting day one, growing in importance as the course advances
- hacking in small teams dedicated to specific functionalities
- some application talks towards the end, not relevant to the hacking

Implementation Goal:

- SLAM, autonomous navigation
- vision-based grasping of (known and/or unknown?) objects from known locations
- placing objects in designated locations
- execution of high-level plans involving the above capabilities

Robots:

- 1 mobile base + arm platform for each group of 3-4 students
- or, 1 UIBK mobile manipulator (homebrew base with DOBOT M1 ? Franka Emika Panda)
- or, TUW Honda mobile manipulator

Schedule

Each session lasts 90 minutes; blank = hacking.

Sessions	Monday	Tuesday	Wednesday	Thursday	Friday
Morning I	Mechatronics of mobile manipulators (Johannes Gerstmayr or Colleague)	Robot Vision (Markus Vincze or Colleague)	Visual Servoing (Antonio Paolillo)		Task Planning (Gerald Steinbauer)
Morning II	Kinematics (Andreas Müller)	Picking and Placing (Justus Piater)	Hacking: Visual Servoing for Pick and Place		Hacking: Task Planning
Afternoon I	Dynamics, Control (Wolfgang Werth)	Human-Robot Interaction and Safety Aspects (Mathias Brandstötter)	Introduction to ROS Navigation Stack (Matteo Saveriano)		Hacking: Team competition
Afternoon II	Hacking: Set-up the robots	Hacking: Path/Motion Planning in ROS	Hacking: Navigation in ROS		
Dinner	on site	on site	on site	in town	-

* confirmed

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