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Marko Zarić

Researcher

Office: T12 (ICT) 2M01

Phone: -

marko.zaric@uibk.ac.at

GitHub LinkedIn

Areas of Interest

- Machine Learning for Robotics
- Human-Robot Interaction
- Motion Planning and Control
- Robot Perception and Computer Vision
- Numerical Mathematics

Positions

- 04.2022 current: Researcher at the Department of Computer Science, Intelligent and Interactive Systems, University of Innsbruck
- 04.2021 11.2021: Digital Signal Processing Engineer at Tesat-Spacecom

Education

- 10.2021 current: MSc in Computer Science at University of Innsbruck
- 10.2016 01.2020: BSc in Mathematics at University of Innsbruck

Projects

• Current: ELSA (ANR-FWF Joint project 2022-2026)

Publications

1. Marko Zaric, Jakob Hollenstein, Justus Piater, Erwan Renaudo, Unsupervised Learning of Effective Actions in Robotics. Austrian Symposium on Al, Robotics and Vision, 2024. [Axiv] [BibTeX]

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