



Erwan Renaudo

Postdoc

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[External homepage](#)

Interested in working with me ? Check the "Teaching and thesis" section.

Areas of Interest

- Autonomous robotics
- Machine Learning for robotics
- Action to behaviour processes in robotics

Positions

- Postdoctoral Researcher at the Department of Computer Science, Intelligent and Interactive Systems, University of Innsbruck (since 2017)
- Postdoctoral Researcher at the Institut des Systèmes Intelligents et de Robotique, AMAC team, University Pierre et Marie Curie (2016)
- PhD Candidate at the Institut des Systèmes Intelligents et de Robotique, AMAC team, University Pierre et Marie Curie (2012-2016)

Education

- 2016 PhD in Computer Science and Robotics from Université Pierre et Marie Curie
- 2012 MSc in Artificial Intelligence and Robotics from Université de Cergy Pontoise
- 2011 MSc in Electronics engineering (french “Diplôme d'ingénieur”) from École Nationale Supérieure d'Électronique et de ses Applications (ENSEA)

Publications

See [Google Scholar](#) and [my external homepage](#)

Teaching and thesis

I offer a set of BSc. and MSc. projects, please have look here if you are interested:

<https://iis.uibk.ac.at/theses/start> Feel free to contact me if we have similar interests. Please attach a CV and tell me in the email what you would like to work on

Remark : If you have questions related to teaching exercises or thesis projects, do not wait for the last moment. Do not expect quick email replies during holidays or week-ends. Send your questions beforehand or ask for an appointment to maximize the chance to get an answer in time.

- First Steps in R (December 2021)
- Introduction to Autonomous and Intelligent Systems [PS 703031 | summer term: 2018]
- [Master Seminar 2](#) [SE 703606 | summer term: 2019]

Projects

I have been employed on these projects (national or european):

- Current: [ELSA](#) (ANR-FWF Joint project 2022-2026)
- Past: [IMAGINE](#) (EU Horizon 2020) (2017-2021)
- Past: [RoboErgoSum](#) (ANR-12-CORD-0030)

Initiatives, Events

- [Rossini](#)

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