

Senka Krivić



I joined Intelligent and Interactives Systems (IIS) lab in February 2014 as a PhD student. There I am working on a [SQUIRREL](#) project and as a teaching assistant of the prosemiar [Introduction to Intelligent and Autonomous Systems](#). My work is under the supervision of Professor Justus Piater and also advised by [Emre Ugur](#) and [Sandor Szedmak](#)

Previously, I obtained a Bachelor and Master degrees in Automatic Control and Electronics at the Faculty for Electrical Engineering, University of Sarajevo. During my studies, I focused on mobile robotics and intelligent control. My bachelor thesis was “Mobile Robot Map Building” and my master thesis was “Biometric Authentication Based on Artificial Neural Networks”, both under supervision of Professor Samim Konjicija.

Research Interests

Robotics, Machine Learning, Robot Learning, Movement Primitives, Computational Intelligence, Optimization

Contact Information

Intelligent and Interactive Systems Institute of Informatik, 2W30 Technikerstr. 21a A-6020 Innsbruck Austria
senka.krivic@uibk.ac.at
Phone (IIS Secretariat) : +43 512 507 53268
Fax (IIS Secretariat): +43 512 53069

Teaching

Universität Innsbruck

- [Introduction to Intelligent and Autonomus Systems \(UIBK link\)](#), spring 2015/2016,
- [Introduction to Intelligent and Autonomus Systems \(UIBK link\)](#), spring 2014/2015,
- [Introduction to Intelligent and Autonomus Systems \(UIBK link\)](#), spring 2013/2014,

University of Sarajevo

- Intelligent Control, fall 2013/2014

Publications

Year	Conferences	Paper	Files
2016	CASE 2016	A Robust Pushing Skill For Object Delivery Between Obstacles , Senka Krivić, Emre Ugur, Justus Piater	casehigh.mp4
2015	ESANN	Learning missing edges via kernels in partially-known graphs , Senka Krivić, Sandor Szedmak, Hanchen Xiong, Justus Piater	dataset
2013	9th ASCC	Optimization based algorithm for correction of systematic odometry errors of mobile robot , Krivic, S.; Mrzic, A.; Velagic, J.; Osmic, N.	
2012	13th MEATRONICS-REM	Haptic paddle and fuzzy based virtual environment model control system as a didactic tool , Krivic, S., Kaknjo, A.; Hujdur, M.; Zubovic, N.; Sokic, E.	
2012	35th MIPRO	Design and implementation of fuzzy controller on embedded computer for water level control , Krivic, S.; Hujdur, M.; Mrzic, A.; Konjicija, S.	
2011	34th MIPRO	Building mobile robot and creating applications for 2D map building and trajectory control , Krivic, S.; Mrzic, A.; Osmic, N.	
Year	Workshops		
2016	UK Planning and Scheduling Special Interest Group	Initial State Prediction in Planning, Senka Krivic, Michael Cashmore, Bram Ridder, Justus Piater, <i>extended abstract</i>	
2015	IROS 2015 workshop on Learning object affordances	Acting on Push Affordances: Adapting Dynamic Movement Primitives Based on Object Behaviour , Senka Krivic, Emre Ugur, Justus Piater, <i>extended abstract</i>	
2014	ARW	Exploiting the Environment for Object Manipulation , Simon Hangl, Senka Krivic, Philipp Zech, Emre Ugur, Justus Piater, <i>Best Student Paper Award</i>	

More Information

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