

Supplementary Material

Hanchen Xiong

November 14, 2013

1 Computing Gradient

Most of computing in this section is based on the matrix calculus rules in (Facker, 2004).

$$\begin{aligned} \{\mathbf{R}^*, \mathbf{t}^*\} &= \arg \max_{\mathbf{R}, \mathbf{t}} \mathbf{O} \\ &= \arg \max_{\mathbf{R}, \mathbf{t}} K(\mathcal{M}_{\mathbf{R}, \mathbf{t}}, \mathcal{S}) \\ &= \arg \max_{\mathbf{R}, \mathbf{t}} \left\{ \frac{1}{m_{\mathcal{M}}} \frac{1}{m_{\mathcal{S}}} \sum_{i=1}^{m_{\mathcal{M}}} \sum_{j=1}^{m_{\mathcal{S}}} \underbrace{\frac{1}{(2\pi)^{3/2}} \exp \left(-\frac{1}{2} \Delta_{ij}' \mathbf{G}_{ij}^{-1} \Delta_{ij} \right)}_{\mathcal{O}_{ij}} \right\} \end{aligned}$$

where $\mathbf{G}_{ij} = \Sigma_{\mathcal{S}}^{(j)} + \mathbf{R} \Sigma_{\mathcal{M}}^{(i)} \mathbf{R}'$ and $\Delta_{ij} = \lambda_{\mathcal{S}}^{(j)} - \mathbf{R} \lambda_{\mathcal{M}}^{(i)} - \mathbf{t}$. By using the mapping:

$$\Omega : [\mathbf{w}, \mathbf{v}]' \rightarrow \{\exp(J(\mathbf{w})\mathbf{R}_0), \mathbf{t}_0 + \mathbf{v}\}, \quad \mathbf{w}, \mathbf{v}, \mathbf{t}_0 \in \mathbb{R}^3, \mathbf{R}_0 \in SO(3)$$

the objective function is dependent only on \mathbf{w} and \mathbf{v} , and the full gradient can be computed as the sum of gradient on each pair of points. So for each pair point $\lambda_{\mathcal{M}}^{(i)}$ and $\lambda_{\mathcal{S}}^{(j)}$, the objective function is as follows:

$$\begin{aligned} \mathcal{O}_{ij} &= \underbrace{|\mathbf{G}_{ij}|^{-1/2}}_{\Delta_{ij}' \mathbf{G}_{ij}^{-1} \Delta_{ij}} \cdot \underbrace{\Sigma_{\mathcal{S}}^{(j)} + \mathbf{R} \Sigma_{\mathcal{M}}^{(i)} \mathbf{R}'}_{\mathbf{G}_{ij}^{-1}} \cdot \underbrace{\exp \left\{ -\frac{1}{2} (\lambda_{\mathcal{S}}^{(j)} - \mathbf{R} \lambda_{\mathcal{M}}^{(i)} - \mathbf{t})' (\Sigma_{\mathcal{S}}^{(j)} + \mathbf{R} \Sigma_{\mathcal{M}}^{(i)} \mathbf{R}')^{-1} (\lambda_{\mathcal{S}}^{(j)} - \mathbf{R} \lambda_{\mathcal{M}}^{(i)} - \mathbf{t}) \right\}}_{\Delta_{ij}} \\ s.t. \quad &\mathbf{R}(\mathbf{w}) = \exp(J(\mathbf{w}))\mathbf{R}_n, \quad \mathbf{t}(\mathbf{v}) = \mathbf{t}_n + \mathbf{v} \\ &\mathbf{w}, \mathbf{v}, \mathbf{t}, \mathbf{t}_n \in \mathbb{R}^3, \quad \mathbf{R}, \mathbf{R}_n \in SO(3) \\ &\Sigma_{\mathcal{M}}^{(i)}, \Sigma_{\mathcal{S}}^{(j)} \text{ are } 3 \times 3 \text{ symmetric positive semidefinite matrices} \end{aligned} \tag{1}$$

the Jacobian vector can be computed as:

$$\frac{\partial \mathcal{O}_{ij}}{\partial \mathbf{v}} = \frac{\partial \mathcal{O}_{ij}}{\partial \Delta_{ij}} \cdot \frac{\partial \Delta_{ij}}{\partial \mathbf{v}_k} = -\mathcal{O}_{ij} \Delta_{ij}' \mathbf{G}_{ij}^{-1} (-1) I_{3,3} = \mathcal{O}_{ij} \Delta_{ij}' \mathbf{G}_{ij}^{-1} \tag{2}$$

$$\frac{\partial \mathcal{O}_{ij}}{\partial \mathbf{w}} = \frac{\partial |\mathbf{G}_{ij}|^{-1/2}}{\partial \mathbf{w}} \cdot \exp(-\frac{1}{2} \Delta_{ij}' \mathbf{G}_{ij}^{-1} \Delta_{ij}) + |\mathbf{G}_{ij}|^{-1/2} \cdot \frac{\partial \exp(-\frac{1}{2} \Delta_{ij}' \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}} \tag{3}$$

the term $\frac{\partial |\mathbf{G}_{ij}|^{-1/2}}{\partial \mathbf{w}}$ in (3) is:

$$\begin{aligned}\frac{\partial |\mathbf{G}_{ij}|^{-1/2}}{\partial \mathbf{w}} &= \frac{\partial |\mathbf{G}_{ij}|^{-1/2}}{\partial |\mathbf{G}_{ij}|} \frac{\partial |\mathbf{G}_{ij}|}{\partial \mathbf{G}_{ij}} \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} \\ &= -\frac{1}{2} |\mathbf{G}_{ij}|^{-3/2} \cdot |\mathbf{G}_{ij}| \text{vec}(\mathbf{G}'_{ij})' \cdot \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} \\ &= -\frac{1}{2} |\mathbf{G}_{ij}|^{-1/2} \text{vec}(\mathbf{G}_{ij})' \cdot \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}}\end{aligned}\quad (4)$$

and the term $\frac{\partial \exp(-\frac{1}{2} \Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}}$ of (3) is:

$$\begin{aligned}\frac{\partial \exp(-\frac{1}{2} \Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}} &= \frac{\partial \exp(-\frac{1}{2} \Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial (\Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})} \cdot \frac{\partial (\Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}} \\ &= -\frac{1}{2} \exp(-\frac{1}{2} \Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij}) \frac{\partial (\Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}}\end{aligned}\quad (5)$$

and

$$\frac{\partial (\Delta'_{ij} \mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}} = \frac{\partial [\Delta'_{ij} (\mathbf{G}_{ij}^{-1} \Delta_{ij})]}{\partial \mathbf{w}} = \Delta'_{ij} \frac{\partial (\mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}} + (\Delta'_{ij} \mathbf{G}_{ij}^{-1}) \frac{\partial \Delta_{ij}}{\partial \mathbf{w}} \quad (6)$$

where term $\frac{\partial (\mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}}$ will be computed as:

$$\begin{aligned}\frac{\partial (\mathbf{G}_{ij}^{-1} \Delta_{ij})}{\partial \mathbf{w}} &= (\Delta'_{ij} \otimes I_{3,3}) \frac{\partial \mathbf{G}_{ij}^{-1}}{\partial \mathbf{w}} + (I_{1,1} \otimes \mathbf{G}_{ij}^{-1}) \frac{\partial \Delta_{ij}}{\partial \mathbf{w}} \\ &= (\Delta'_{ij} \otimes I_{3,3}) \frac{\partial \mathbf{G}_{ij}^{-1}}{\partial \mathbf{G}_{ij}} \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} + (I_{1,1} \otimes \mathbf{G}_{ij}^{-1}) \frac{\partial \Delta_{ij}}{\partial \mathbf{w}} \\ &= (\Delta'_{ij} \otimes I_{3,3}) [-(G_{ij}^{-1} \otimes G_{ij}^{-1})] \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} + (I_{1,1} \otimes \mathbf{G}_{ij}^{-1}) \frac{\partial \Delta_{ij}}{\partial \mathbf{w}} \\ &= -(\Delta'_{ij} G_{ij}^{-1} \otimes G_{ij}^{-1}) \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} + \mathbf{G}_{ij}^{-1} \frac{\partial \Delta_{ij}}{\partial \mathbf{w}}\end{aligned}\quad (7)$$

and then we can compute $\frac{\partial \Delta_{ij}}{\partial \mathbf{w}}$ which appears in (6)(7) as:

$$\begin{aligned}\frac{\partial \Delta_{ij}}{\partial \mathbf{w}} &= \frac{\partial [-\exp(J(\mathbf{w})) \mathbf{R}_n \lambda_{\mathcal{M}}^{(i)}]}{\partial \exp(J(\mathbf{w}))} \cdot \frac{\partial \exp(J(\mathbf{w}))}{\partial J(\mathbf{w})} \cdot \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \\ &= -(\lambda_{\mathcal{M}}^{(i)'} \mathbf{R}'_n \otimes I_{3,3}) \cdot I_{9,9} \cdot \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \\ &= J(\mathbf{R}_n \lambda_{\mathcal{M}}^{(i)})\end{aligned}\quad (8)$$

the term $\frac{\partial \mathbf{G}}{\partial \mathbf{w}}$ which appears in (4)(6) is computed:

$$\begin{aligned}\frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} &= \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{R}} \frac{\partial \mathbf{R}}{\partial \mathbf{w}} = \frac{\partial (\mathbf{R} \Sigma_{\mathcal{M}}^{(i)} \mathbf{R}')}{\partial \mathbf{R}} \frac{\partial \mathbf{R}}{\partial \mathbf{w}} = \frac{\partial ((\mathbf{R}(\mathbf{K}\mathbf{K}')\mathbf{R}')} {\partial \mathbf{R}} \frac{\partial \mathbf{R}}{\partial \mathbf{w}} \\ &= \frac{\partial ((\mathbf{R}\mathbf{K})(\mathbf{R}\mathbf{K})')}{\partial \mathbf{R}\mathbf{K}} \cdot \frac{\partial \mathbf{R}\mathbf{K}}{\partial \mathbf{R}} \cdot \frac{\partial \mathbf{R}}{\partial \mathbf{w}} \\ &= (I_{9,9} + T_{3,3})(\mathbf{R}\mathbf{K} \otimes I_{3,3}) \cdot (\mathbf{K}' \otimes I_{3,3}) \cdot \frac{\partial \mathbf{R}}{\partial \mathbf{w}} \\ &= (I_{9,9} + T_{3,3})(\mathbf{R}\mathbf{K}\mathbf{K}' \otimes I_{3,3}) \cdot \frac{\partial \mathbf{R}}{\partial \mathbf{w}} \\ &= (I_{9,9} + T_{3,3})(\mathbf{R}\Sigma_{\mathcal{M}}^{(i)} \otimes I_{3,3}) \cdot \frac{\partial \mathbf{R}}{\partial \mathbf{w}}\end{aligned}\quad (9)$$

where vectorization operator $\text{vec}(\cdot)$ and $T_{n,n}$ is defined in (Facker, 2004). Finally, $\frac{\partial \mathbf{R}}{\partial \mathbf{w}}$ is computed:

$$\frac{\partial \mathbf{R}}{\partial \mathbf{w}} = \frac{\partial [\exp(J(\mathbf{w}) \mathbf{R}_n)]}{\partial \exp(J(\mathbf{w}))} \cdot \frac{\partial \exp(J(\mathbf{w}))}{\partial J(\mathbf{w})} \cdot \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} = (\mathbf{R}'_n \otimes I_{3,3}) \cdot \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \quad (10)$$

thus we can rewrite the entries of Jacobian vector by substituting (4)(6)(7)(8)(9)(10) into (2)(3) :

$$\frac{\partial \mathcal{O}_{ij}}{\partial \mathbf{v}} = \mathcal{O}_{ij} \Delta'_{ij} \mathbf{G}_{ij}^{-1} \quad (11)$$

$$\begin{aligned} \frac{\partial \mathcal{O}_{ij}}{\partial \mathbf{w}} = & \left\{ \left(\frac{1}{2} (\Delta'_{ij} \mathbf{G}_{ij}^{-1}) \otimes (\Delta'_{ij} \mathbf{G}_{ij}^{-1}) - \text{vec}(\mathbf{G}_{ij}^{-1})' \right) \right. \\ & \left. \cdot \frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} - \Delta'_{ij} J(\mathbf{R}_n \lambda_m^{(i)}) \right\} \mathcal{O}_{ij} \end{aligned} \quad (12)$$

where

$$\frac{\partial \mathbf{G}_{ij}}{\partial \mathbf{w}} = (\mathbf{I}_9 + T_{3,3})(\mathbf{R} \boldsymbol{\Sigma}_{\mathcal{M}}^{(i)} \boldsymbol{\Sigma}' \otimes \mathbf{I}_3) \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \quad (13)$$

By summing up gradients computed on all pairs, we can get:

$$\frac{\partial \mathbf{O}}{\partial \mathbf{v}} = \sum_{i=1, j=1}^{m_{\mathcal{M}}, m_{\mathcal{S}}} \frac{1}{(2\pi)^{3/2}} \frac{\partial \mathcal{O}_{ij}}{\partial \mathbf{v}} \quad \frac{\partial \mathbf{O}}{\partial \mathbf{w}} = \sum_{i=1, j=1}^{m_{\mathcal{M}}, m_{\mathcal{S}}} \frac{1}{(2\pi)^{3/2}} \frac{\partial \mathcal{O}_{ij}}{\partial \mathbf{w}} \quad (14)$$

References

Facker, P. (2004, April). Notes on Matrix Calculus.